

## 14. PLC MEMORY

### Topics:

- PLC memory types: program and data
- Data types: boolean, input, output, bit, char, counter, integer, floating point, etc.
- Memory addressing: words, bits, data files, expressions, formal names and indices.

### Objectives:

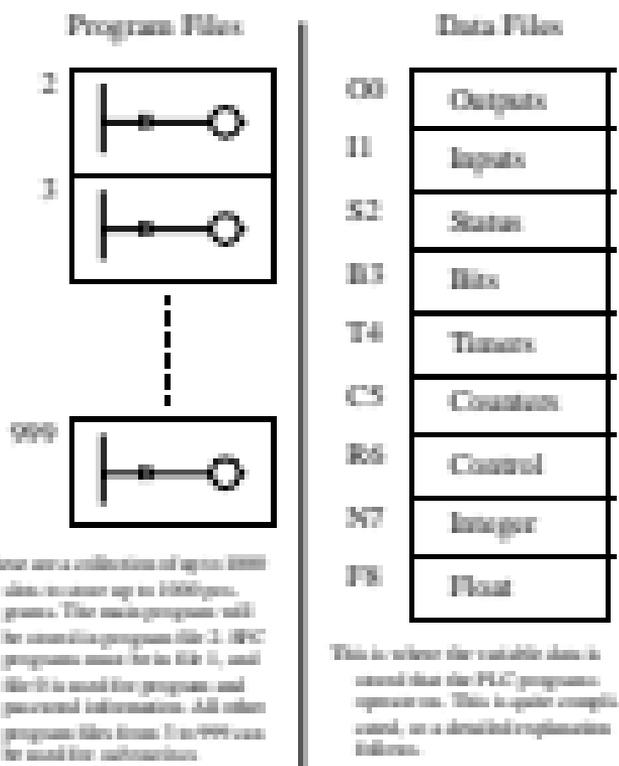
- To know the basic memory types available
- To be able to use addresses for locations in memory

### 14.1 INTRODUCTION

Advanced ladder logic functions allow controllers to perform calculations, make decisions and do other complex tasks. Timers and counters are examples of ladder logic functions. They are more complex than basic input contacts and output coils and they only operate when available in the memory of the PLC. The memory of the PLC is organized to hold different types of programs and data.

### 14.1 MEMORY ADDRESSING

The memory in a PLC is organized by data type as shown in Figure 14.1. There are two fundamental types of memory used in Allen-Bradley PLC's - Program and Data memory. Memory is organized into blocks of up to 1000 elements in an array called a file. The Program file holds programs, such as ladder logic. There are eight data files defined by default, but additional data files can be added if they are needed.



This is where the variable data is stored that the PLC programs operate on. This is quite complex, and a detailed explanation follows.

Figure 14.1 PLC Memory

### 14.1 PROGRAM FILES

In a PLC-1 the three base program files, from file 1, are defined by default. File 0 contains system information and identification for changes, and file 1 is reserved for IFCs. File 2 is available for user programs, and the PLC will run the program in file 1 by default. Other program files can be added from file 1 to 999. Typical examples for creating others

programs are the information.

When a user creates a ladder logic program with programming software, it is converted to a mnemonic-like form, and then transferred to the PLC, where it is stored in a program file. The contents of the program memory cannot be changed while the PLC is running. If, while a program is running, a user corrects it with a new program, serious problems could arise.

## DATA FILES

Data files are used for storing different information types, as shown in Figure 14.2. These locations are numbered within 0 to 999. The letter is chosen to indicate the data type. For example, *FX* is used as floating point numbers in data file *X*. Numbers are not given for *X* and *I*, but they are implied to be *00* and *01*. The numbers that follow the letter indicate location numbers. Each file may contain from 0 to 999 locations that may store values. For the input *I* and output *O* files the locations are considered as physical locations on the PLC using rack and slot numbers. The addresses that can be used will depend upon the hardware configuration. The master *CI* file is more complex and is discussed later. The other memory locations are simply stores to store data in. For example, *FX-00* would hold the *00* value in the *00*th file which is floating point numbers.



Figure 14.2 Data Files for an Allen Bradley PLC-5

Only the first three data files are listed ( $T:0$ ,  $T:1$  and  $T:2$ ), all of the other data files can be assumed. It is also reasonable to have multiple data files with the same data type. For example, there could be two files for integer numbers ( $T:0$  and  $T:01$ ). The length of the data files can be from 0 up to 999 as shown in Figure 11.1. Also, these files are often made smaller to save memory.

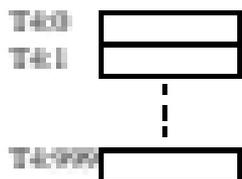


Figure 11.1 Locations in a Data File

Figure 11.1 shows the default data files for a PDC-3. There are many additional data types, a full list is shown in Figure 11.4. Some of the data types are complex and contain multiple data values, including  $ST$ ,  $C$ ,  $WC$ ,  $PH$ ,  $B$ ,  $BC$ , and  $V$ . Several data types require integers like the accumulator and parent, and  $T1$ ,  $DS$  and  $DS$  files are required. Other data types are based on single bits, 8 bit bytes and 16 bit words.

Type	Length (bytes)
A - ASCII	10
B - bit	256
BT - block transfer	4
C - control	1
CS - ASCII	1
F - floating point	2
HC - message	96
N - integer (signed) assigned, 16 complements (ASCII)	1
NS - PDU completion	62
R - control	1
SC - SSC name	1
ST - ASCII string	62
T - time	1

**NOTE:** Memory is a general term that refers to both file modifications. The term *file-specific* or *PDU* manufacturers and is not widely recognized elsewhere.

Figure 14.1 Allen-Bradley Data Types

When using data file modifications we need to add the information with an address. The simplest data addresses are data file (you have used these for block inputs and outputs already). An example of Address file is shown in Figure 14.5. Memory files are usually indicated with a forward slash followed by a file number (i). The first example is from an input word I:000, the third input is indicated with the file address 001. The second example is for a control I:3 done file 000. This could also be replaced with I:3:0:0 to get equivalent results. The 000 notation, and others like it are used to simplify the task of programming. The example R:00 will get the fourth bit in 0 memory 001. For file memory the slash is unnecessary, because the data type is already file.

**lit** . individual bits in a word . this is like addressing a single output in a data bus

- l00000** . the third input bit from input word l0000
- l00000** . the 0th bit of a constant
- l000** . the fourth bit in the memory

**lit000** . three bit address, especially inputs and outputs are addressed using **lit**. This often leads to confusion over word addresses. For example if you want the 10th output bit, or bit 10, you would need to use 010 as word to address it properly.

lit	000	001	010	011	100	101	110	111	000	001	010	011	100	101	110	111
00	00	01	10	11	00	01	10	11	00	01	10	11	00	01	10	11

Figure 14.7 Bit-Level Addressing

Other words can be addressed like shown in Figure 14.6. These values will usually be assumed to be 32-bit constants, but some functions may assume otherwise. The first example shows a simple integer memory value. The next example gets up to inputs from word 0 to each word, i.e. a single word. The last two examples are more complex and they access the accumulator and port values for a time. Here a ‘**l**’ is used as the ‘**r**’ was used for the memory to indicate this is integer. The last two examples don’t include ‘**r**’ because they are both integer value types. Other types of word addressing are possible, including floating point numbers.

**intgr word** . 32-bit word manipulated as an integer

- l000** . the 0th value from integer memory
- l0000** . an integer with all input values from an input word
- lit0.ACC** . the accumulator value for a time
- lit0.PORT** . the port value for a time

Figure 14.8 Integer Word Addressing

Some values do not always need to be stored in memory, they can be done directly. Figure 14.7 shows an example of two different data values. The first is an integer, the second is a real number. Hexadecimal numbers can be indicated by following the number with **H**, a floating point is also needed when the first digit is **d**, **R**, **C**, **B**, **E** or **F**. A binary number is indicated by adding a **B** to the end of the number.

**Local data values** - a data value can be provided without stating it is memory.

```

% - integer
%L - floating point number
%DB - a decimalised value of
%DBDB - a binary number 000000
    
```

**Figure 11.7** Local Data Values

Sometimes we will want to refer to an array of values, as shown in Figure 11.8. This data type is indicated by beginning the number with a percent or hash sign (%). The first example describes an array of floating point numbers starting in file 5 at location 5. The second example is for an array of integers in file 7 starting at location 5. The length of the array is determined by where.

**%L** - the first location of an array of data values.

```

%DB 5 - indicates group of values starting at DB 5
%L 5 - indicates group of values starting at L 5
    
```

**Figure 11.8** File Addressing

Indirect addressing is a method for allowing a variable in a data address, as shown in Figure 11.9. The indirect (variable) part of the address is shown between brackets, [ ], and [ ] is replaced by the name of the address and in both an indirect address it will look in the specified memory location, and go that number in place of the indirect address. Consider the first example below it 000(0000) is the value in the integer memory location 000 is 00, then the address becomes 000(00). The other examples are very similar. This type of technique is very useful when making programs that can be adapted for different outputs, by changing a data value in our memory. Because the program can follow a new set of data.

**indirect** - another memory location can be used in the description of a location.

```

1000(R7)Q . If R7's location contains 0 this will become 1000+0
1(R7)I(0) . If the integer memory location contains 1 this will become 1000+0
R(R7)I . If the integer memory location contains 1 the file will read a 1000
N(R7)Q 0 . If the number in R7 is 0 the file address becomes N+0
    
```

Figure 14.9 Indirect addressing

Expressions allow address and functions to be typed in and interpreted when the program is run. The example in Figure 14.10 will get following pointer number from file R, location 1, perform a sine transformation, and then add 1.5. The same thing is not interpreted until the PLC is running, and if there is an error it may not occur until the program is running - so use this function carefully.

**expression** - a text string that describes a complex operation.

```

"sin(R1) + 1.5" - a simple calculation
    
```

Figure 14.10 Expression Data Values

These data types and addressing modes will be discussed more as applicable functions are presented later in this chapter and book. Floating point numbers, expressions and indirect addressing may not be available on older or lower cost PLCs.

Figure 14.11 shows a simple example ladder logic with functions. The basic operation is available while input 0 is true the functions will be performed. The first statement will move (MOV) the file address of 100 into integer memory R7-0. The next move function will copy the value from R7-0 to R7-1. The third statement will add integer value in R7-0 and R7-1 and store the results in R7-1.

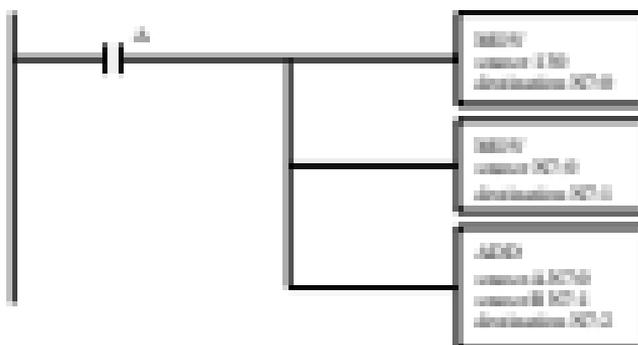
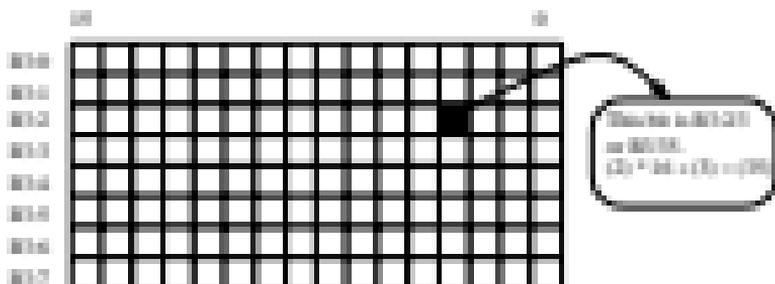


Figure 14.11 An Example of Ladder Logic Functions

### 14.1.1 User-Bit Memory

Individual data bits can be accessed in the bit memory. These can be very useful when developing such infrequent cases that do not directly relate to an output or input. The bit memory can be accessed with individual bits or with integer words. Examples of bit addresses are shown in Figure 14.12. The single Markwell bit is identified word B1-2 and it is the 10th bit (10), so it can be addressed with B1-201. Overall, it is the 10th bit, so it could be addressed with B110.



Other Examples: 001000 = 0 0 00  
 001001 = 0 0 01  
 001002 = 0 0 02  
 001003 = 0 0 03  
 001004 = 0 0 04  
 etc...

Figure 11.11 Bit Memory

This method can also be used to access bits in integer memory also.

### 11.1.2 Integer Counter Memory

Previous chapters have discussed the operations of timers and counters. The ability to address their memory directly allows some powerful tests. Recall that by default timers are stored in the 00 file. The bits and words for timers are:

- 00 - timer enabled bit (bit 00)
- 01 - timer timing bit (bit 01)
- 02 - timer done bit (bit 02)
- 000 - present word
- 00C - accumulated time word

Counters are stored in the 01 file and they have the following bits and words.

**CS0** - counter for bit 13  
**CS1** - counter down for bit 14  
**CS2** - counter down for bit 15  
**CS3** - overflow for bit 12  
**CS4** - underflow for bit 11  
**PRE** - preset word  
**ACC** - accumulated count word

As discussed before we can access timer and counter bits and words using the proper notation. Examples of these are shown in Figure 14.13. The bit values can only be read, and therefore be changed. The preset and accumulated words can be read and overwritten.

#### Words

**TIMPRE** - the preset value for timer T10  
**TIMACC** - the accumulated value for timer T10  
**CSMPRE** - the preset value for counter CS0  
**CSMACC** - the accumulated value for counter CS0

#### Bits

**T10EN** - indicates when the input to timer T10 is true  
**T10TT** - indicates when the timer T10 is counting  
**T10DN** - indicates when timer T10 has reached the maximum  
**CS0CN** - indicates when the count-up instruction is true for CS0  
**CS0CD** - indicates when the count-down instruction is true for CS0  
**CS0DN** - indicates when the counter CS0 has reached the preset  
**CS0DN** - indicates when the counter CS0 has reached the maximum value (32767)  
**CS0UN** - indicates when the counter CS0 has reached the minimum value (-32768)

Figure 14.13 Examples of Timer and Counter Addresses.

Consider the simple ladder logic example in Figure 14.14. It shows the use of a timer timing 0.5 s to roll on the timer when a door light has gone true. While the timer is counting, the bit will stay true and keep the timer counting. When it reaches the 0.5 second delay the 0.5 bit will turn off. The next line of ladder logic will turn on a light while the timer is counting for the first 0.5 second.

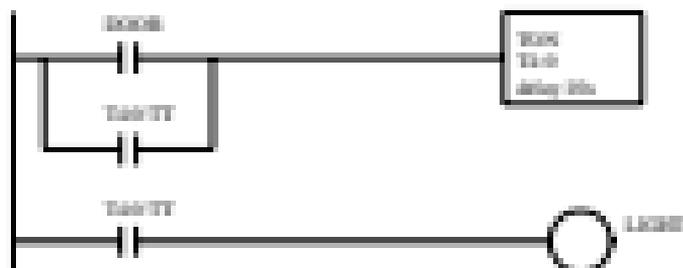


Figure 12.14 Door Light Example

### 12.4.3.1 Multiple Status Bits (for PLCs and Micrologix)

Status memory allows a program to check the RLC operation, and also make some changes. A selected list of status bits is shown in Figure 12.15 for Allen-Bradley Micrologix and PLC-5/PLC-3. More complete lists are available in the manuals. For example the first four bits (S1-04) indicate the results of calculations, including carry, overflow, zero and sign-bit flags. The S1-05 will become zero when the PLC is turned on - this is the first zero bit. The time for the last zero will be stored in S1-06. The time until device can be accessed will come from locations S1-08 to S1-20.

- Q1.01 zero in math operation
- Q1.02 overflow in math operation
- Q1.03 zero in math operation
- Q1.04 sign in math operation
- Q1.05 low word of program file
- Q1.06 the execution time (ms)
- Q1.07 year
- Q1.08 month
- Q1.09 day
- Q1.10 hour
- Q1.11 minute
- Q1.12 second
- Q1.13 watchdog output
- Q1.14 bank number file number
- Q1.15 IPI (programmable serial interrupt) output
- Q1.16 IPI file number
- Q1.17 ILCI (ILCI-14, ILCI-16, IPI) (Program and/or Input Interrupt) settings
- Q1.18 IPI low word time(ms)
- Q1.19 communication error time (ms)

Figure 14.11 Inputs Bits and Words for Micrologix and PLC-5s

The other status words allow more complex control of the PLC. The watchdog timer allows a clear to be set in Q1.08 so that if the PLC is inactive it indicates the PLC will give a fault condition. This is very important for diagnostic purposes. When a fault occurs the program number in Q1.09 will show. For example, if you have a divide by zero fault, you can run a program that returns from the error, if there is no program the PLC will fault. The locations from Q1.05 to Q1.07 are used for interrupts. Interrupts can be used to run programs at fixed time intervals, or when inputs change.

## 14.4.4 User Function Control Memory

Single ladder logic functions can complete operations in a single scan of ladder logic. Other functions such as timers and counters will require multiple ladder logic scans to finish. While timers and counters have their own memory for control, a generic type of control memory is defined for other functions. This memory controls the bits and words in Figure 14.16. Any given function will only use some of the values. The meaning of particular bits and words will be described later when discussing specific functions.

```

EN - enable bit (bit 15)
EW - enable word (bit 16)
EX - exec bit (bit 17)
EM - empty bit (bit 18)
EB - even bit (bit 19)
EA - address bit (bit 20)
ES - inhibit bit (bit 21)
ED - shared bit (bit 22)
LEW - length word
PEW - position word
    
```

Figure 12.26 Bits and Words for Control Memory

### 12.4.4 Integer Memory

Integer memory is 32-bit words that are normally used as 32-bit complement numbers that can store data values from -2147483648 to +2147483647. When fractional fractions are supplied they are truncated to the nearest number. These values are normally stored in 32-bit by default, however blocks of integer memory are often created in other locations, such as 60-bit integer memory created for word buffers.

### 12.4.5 Floating Point Memory

Floating point memory is available in several and higher cost (64-bit) bit configurations on the Micrologix. This memory stores real numbers and words, with 7 digits of accuracy over a range from  $\pm 1.7E+30$  to  $\pm 1.7E-30$ . Floating point memory is stored in 32-bit by default, but other floating point numbers can be stored in other locations. Bit level access is not permitted for words/for these numbers.

## 12.5 SUMMARY

- Program files store users programs in files 2 - 999.
- Data files are available to users and utilize 0-999 locations long.
- Default data types on a PLC include Boolean (ON/OFF), Integer (I/O), Status (SD), Bit (B1), Timer (T1), Counter (C1), Control (B1), Integer (N1) and Point (P1).
- Other memory types include Block Transfer (BT), ASCII (A), ASCII String (ST), ASCII (S), Message (M), PID Control (PI), MPC Series (PC).

- In memory locations a 'T' indicates bit, 'I' indicates a word.
- Indirect addresses will substitute memory values between [T], [I].
- Files can also be used and are indicated with 'F'.
- Expressions allow equations to be typed in.
- Literal values for binary and hexadecimal values are followed by B and H.

## 6.6 PRACTICE PROBLEMS

1. Can PLC memory be set with 0 or instead of true?
2. How many types of memory does a PLC have?
3. What are the default program memory locations?
4. How many types of number bases are used in PLC memory?
5. How are timer and counter memory similar?
6. What types of memory cannot be changed?
7. Develop ladder logic for a car door lock fault safety system. When the car door is open, no the number 1 on door key a buzzer will sound for 5 seconds if the key has been inserted. A red light will be activated on when the door is open and ring on for 10 seconds after it is closed, unless a key has started the ignition system.
8. Look at the manuals for the main memory in your PLC and find the first word location.
9. Write ladder logic for the following problem description. When button A is pressed a value of 1000 will be stored in N7:0. When button B is pressed a value of -345 will be stored in N7:1, when it is not pressed the value of 99 will be stored in N7:0. When button C is pressed N7:0 will be added, and the result will be stored in N7:2.
10. Using the main memory locations, write a program that will flash a light for the first 10 seconds after it has been turned on. The light should flash once a second.
11. How many words are required for timer and counter memory?

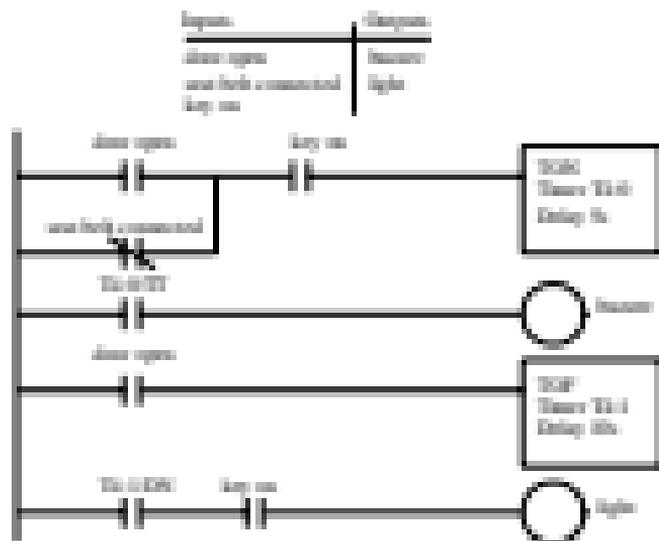
## 6.7 PRACTICE PROBLEM SOLUTIONS

1. yes, for example the output word would be addressed as I:0/00.
2. There are 10 different memory types, 8 of these can be defined by the user for data files.

between I and Q0.

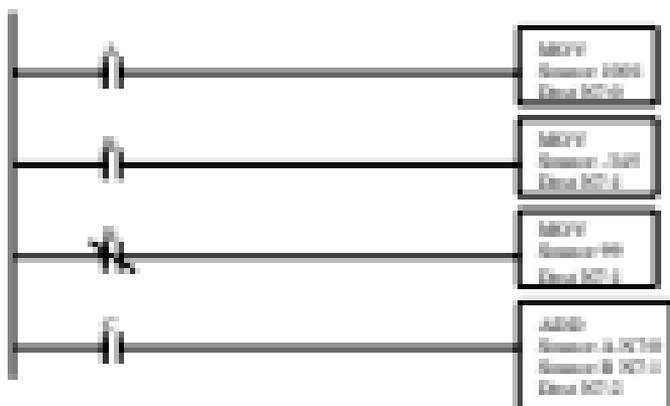
3. Programs files 0 and 1 are reserved for system functions. File 2 is the default ladder logic program, and files 3 to 999 can be used for other programs.
4. Binary, word, BCD, Z-counter, signed binary, floating point, bit, hexadecimal
5. bits are similar. The store and compare commands both use results for the accumulator and program, and they use bits to reach the status of the functions. These bits are common but different, but parallel to function.
6. Inputs cannot be changed by the program, and some of the status bits/words cannot be changed by the user.

7.

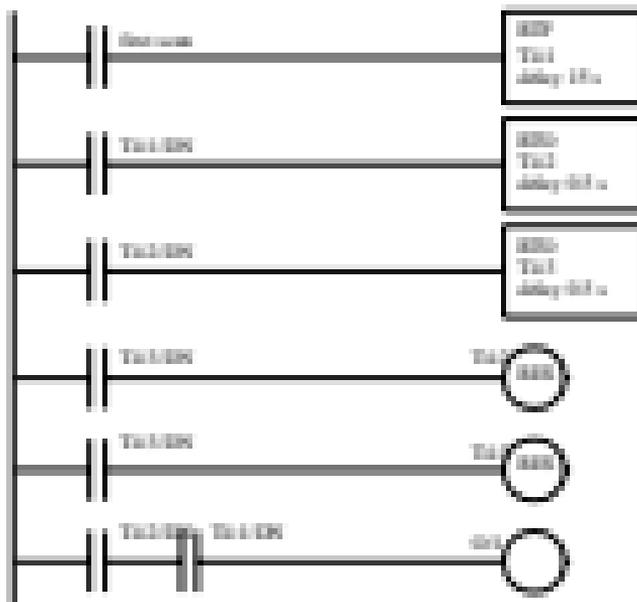


8. K0 1-14 for micrologix, K0 1-15 for PLC 1.

46.



10.



11. How memory words are used for address in a system

**11B. ASSIGNMENT PROBLEMS**

1. Briefly list and describe the different methods for addressing values (e.g., word, bit, block, etc.).
2. Could some 'C' and some 'C' memory types be replaced with some 'W' memory types? Explain your answer.