

14. PLC MEMORY

Topics:

- PLC Memory types program and data
- Data types: boolean, input, output, bit, char, counter, integer, floating point, etc.
- Memory addressing: words, bits, data files, expressions, formal names and indicators.

Objectives:

- To know the basic memory types available
- To be able to use addresses for locations in memory

14.1 INTRODUCTION

Advanced ladder logic functions allow controllers to perform calculations, make decisions and do other complex tasks. Timers and counters are examples of ladder logic functions. They are more complex than basic input contacts and output coils and they rely upon data stored in the memory of the PLC. The memory of the PLC is organized to hold different types of programs and data.

14.2 MEMORY ADDRESSING

The memory in a PLC is organized by data type as shown in Figure 14.1. There are two fundamental types of memory used in Allen-Bradley PLC's . Program and Data memory. Memory is organized into blocks of up to 1000 elements in an array called a file. The Program file holds programs, such as ladder logic. There are eight data files defined by default, but additional data files can be added if they are needed.

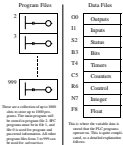


Figure 14.1 PLC Memory

14.2 PROGRAM FILES

In a PLC, the three basic program files, from file 1, are defined by default. File 0 contains system information and is identical for all PLCs, and file 1 is reserved for the IFC. File 2 is available for user programs and the PLC will run the program in file 1 by default. Other program files can be added from file 1 to 999. Typical systems also contain others

programs are the information.

When a user creates a ladder logic program with programming software, it is converted to a mnemonic-like form, and then transferred to the PLC, where it is stored in a program file. The contents of the program memory cannot be changed while the PLC is running. If, while a program was running, it was corrupted with a new program, serious problems could arise.

DATA FILES

Data files are used for storing different information types, as shown in Figure 14.2. These locations are numbered from 0 to 999. The letter in front of the number indicates the data type. For example, *PI* is used as floating point numbers in data file 1. Numbers are not given for 0, usually, but they are implied to be 000 and 01. The number that follows the : is the location number. Each file may contain from 0 to 999 locations that may store values. For the input 0 and output 0 files the locations are connected to physical locations on the PLC using rack and slot numbers. The addresses that can be used will depend upon the hardware configuration. The output *CI* file is more complex and its description follows. The other memory locations are simply data to store data in. For example, *PI* 01 would indicate the 001 value in the floating file which is floating point numbers.



Figure 14.2 Data Files for an Allen/Bradley PLC-5

Only the first three data files are listed (*0*, *1*, and *100*); all of the other data files can be omitted. It is also reasonable to have multiple data files with the same data type. For example, there could be two files for integer numbers (*00* and *01*). The length of the data files can be from 0 up to 999 as shown in Figure 14.3. Also, these files are often made smaller to save memory.



Figure 14.3: Locations in a Data File

Figure 14.3 shows the default data files for a P&C. There are many additional data types; a full list is shown in Figure 04.4. Some of the data types are complex and contain multiple data values, including *00*, *01*, *05*, *06*, *07*, and *1*. Several data types require integers for the accumulators and points, and *T0*, *05* and *06* files are required. Other data types are based on single bits, 0 for false and 1 for true.

Type	Length (bytes)
A : ASCII	10
B : int	2146
BT : block transfer	4
C : control	1
CS : BCD*	1
F : floating point	2
HC : message	96
H : integer (signed) assigned, is complement, BCD*	1
HS : PDA-transfer	62
I : control	1
IC : ISC name	1
IT : ASCII string	16
T : time	1

NOTE: Memory is a general term that refers to both data and instructions. This term *glibc* is specific to *libc* manufacturers and is not widely recognized elsewhere.

Figure 14.1 Addressing Data Types

When using data files and functions we need to mark the information with an address. The simplest data addresses are data files (you have used these for books, tapes, and output already). An example of Address file is shown in Figure 14.5. Memory files are usually indicated with a forward slash followed by a file number. The first example is from an input card 1/000, the third input is indicated with the file address /02. The second example is for a control /13 data file /05. This could also be replaced with /13/017 to get operation results. The /00 notation, and others like it are used to simplify the task of programming. The example 0.10 will get the fourth file in file memory 01. For file memory the slash is not needed, because the data type is already file.

lit - individual bits in memory - this is like addressing a single output as a data bit

l0000000 - the first input bit from input word l0000

l000000 - the 0th bit of a constant

l000 - the fourth bit in bit memory

l0000 - four bit address, especially inputs and outputs are addressed using such.
This often leads to confusion, errors and mistakes. For example if you want the 0th output bit, or bit 0, you would need to use 00 as used as address is properly.

lit	0bit	1bit	2bit	3bit	4bit	5bit	6bit	7bit	8bit	9bit	10bit	11bit	12bit	13bit	14bit	15bit
00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	17

Figure 14.3 Bit Level Addressing

Other words can be addressed like shown in Figure 14.6. These values will usually be assumed to be 32-bit values, but some functions may assume otherwise. The first example shows a single integer memory value. The next example gets up to inputs (from and to each way), e.g. input word. The last two examples are more complex, and they access the accumulator and port values for outputs. Here a "0" is used as the "0" was used for bit memory to indicate this is an integer. The first two examples don't mention "0" because they are both integer value types. Other types of word addressing are possible, including floating point numbers.

integer word - 32bit value manipulated as an integer

l0000 - the 0th value from integer memory

l00000 - an integer with all input values shown as input word

l0000000 - the accumulator value for a timer

l00000000 - the port value for a timer

Figure 14.6 Integer Word Addressing

Some values do not always need to be stored in memory, they can be defined directly. Figure 14.7 shows an example of three different data values. The first is an integer, the second is a word value. Hexadecimal numbers can be indicated by following the number with **H**, a leading zero is also needed when the first digit is **a**, **b**, **c**, **d**, **e** or **f**. A binary number is indicated by adding a **B** to the end of the number.

Real data values - a data value can be provided without stating it is memory.

```

R - real integer
R.1 - addressing pointer number
00000...a decimalised value 00
00000000...a binary number 00/000000
    
```

Figure 14.7 - Literal Data Values

Sometimes, we will want to refer to an array of values, as shown in Figure 14.8. This data type is indicated by beginning the number with a period or lead sign 'P'. The first example describes an array of floating point numbers starting in file 5 at location 5. The second example is for an array of integers in file 7 starting at location 5. The length of the array is determined elsewhere.

file - the first location of memory of data values.

```

000.5 - indicates a group of values starting at 000.5
007.0 - indicates a group of values starting at 007.0
    
```

Figure 14.8 - File Addressing

Indirect addressing is a method of allowing a variable in a data address, as shown in Figure 14.9. The **indirect** (variable) part of the address is shown between brackets '[' and ']'. If a PLC is looking at an address and it finds an indirect address it will look in the specified memory location, and go that number in place of the indirect address. Consider the first example below 0.000(007.0) if the value in the integer memory location 007.0 is 05, then the address becomes 0.000(05). The other examples are very similar. This type of technique is very useful when making programs that can be adapted for different setups... by changing a data value in our memory location the program can follow a new set of data.

indirect - another memory location can be used in the description of a location.

```

I000[ST-2] . If ST-2 location contains 0 this will become I000/00
I[ST-1]001 . If the integer memory location contains 1 this will become I000/001
M[ST-1] . If the integer memory location contains 1 the file will store a 0/001
M[ST0]0 . If the number in ST0 is 0 . If the file address becomes M100
    
```

Figure 14.9 Indirect addressing

Expressions where addresses and functions are brought in and interpreted when the program is run. The example in Figure 14.10 is all gets following point number from file 0, location 1, performs a sine transformation, and then add 1.1. The next entry is not there, period until the PLC is running, and if there is an error, it may not occur until the program is running, so use this function cautiously.

expression - a text entry that describes a complex operation.

```

'sin(P0.1) + 1.1' - a simple calculation
    
```

Figure 14.10 Expression Data Values

These data types and addressing modes will be discussed more as applicable functions are presented later in this chapter and book. Floating point numbers, expressions and indirect addressing may not be available on older or lower cost PLCs.

Figure 14.11 shows a simple example ladder logic with functions. The basic operation is each time input 0 is true the functions will be performed. The first statement will move (MOV) the decimal value of 200 into integer memory ST-0. The next move function will copy the value from ST-0 to ST-1. The third statement will add integer value in ST-0 and ST-1 and store the results in ST-1.



Figure 14.2: An Example of Ladder Logic Functions

14.4.1 User Bit Memory

Individual data bits can be accessed in the bit memory. These can be very useful when dealing with internal states that do not directly relate to an output or input. The bit memory can be accessed with individual bits, or with integer words. Examples of bit addresses are shown in Figure 14.12. The single Macromotion bit is identified word B3.2 and it is the 15th bit (0), so it can be addressed with B3.200. Overall, it is the 15th bit, with modification for address word B3.00.

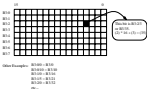


Figure 11.12 Bit Memory

This method can also be used to access bits in integer memory also.

HALT Timer Counter Memory

Previous chapters have discussed the operations of timers and counters. The ability to address their memory directly allows some powerful tools. Recall that by default timers are stored in the 20-bit file. The bits and words for timers are:

- TR - timer enabled bit (bit 14)
- TR - timer timing bit (bit 15)
- TR - timer done bit (bit 16)
- PRD - preset word
- ACC - accumulated time word

Counters are stored in the 03-bit file and they have the following bits and words.

```

COUNT . count up bin (bin 11)
COUNT . count down bin (bin 11)
BIN . counter done bin (bin 11)
COUNT . overflow bin (bin 12)
COUNT . underflow bin (bin 10)
PREL . present word
ACC . accumulated count word
    
```

As discussed before we can count down and count up bin and word using the proper notation. Examples of these are shown in Figure 14.13. The bin values can only be read, and shouldn't be changed. The present and accumulated can be read and overwritten.

Words

```

T0PREL . the present value for timer T0
T0ACC . the accumulated value for timer T0
C0PREL . the present value for counter C0
C0ACC . the accumulated value for counter C0
    
```

Bits

```

T0EN . indicates when the input to timer T0 is true
T0TT . indicates when the timer T0 is counting
T0DN . indicates when timer T0 has reached the maximum
C0EN . indicates when the count up instruction is true for C0
C0UD . indicates when the count down instruction is true for C0
C0MN . indicates when the counter C0 has reached the present
C0MX . indicates when the counter C0 has reached the maximum value (32767)
C0MXN . indicates when the counter C0 has reached the minimum value (-32768)
    
```

Figure 14.13 Examples of Timer and Counter Addressing

Consider the simple ladder logic example in Figure 14.14. It shows the use of a timer timing 10 ms to tell us the timer when a door light has gone on. While the timer is counting, the bit will say true, and keep the timer counting. When it reaches the 10 second delay the 10bit will turn off. The new line of ladder logic will turn on a light while the timer is counting for the first 10 seconds.

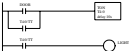


Figure 14.14 Door Light Example

14.1.3 PLC Status Bits (for PLCs and Micrologix)

Status memory allows a program to check the PLC operation, and also make some changes. A selected list of status bits is shown in Figure 14.15 for Allen-Bradley Micrologix and PLC-5 PLCs. Many complete lists are available in the manuals. For example, the first time this I/O bit indicates the results of calculations, including carry, overflow, zero and negative flags. This I/O bit will become more useful when the PLC is turned on - this is the first scan bit. The time for the last scan will be stored in I/O. This data and check can be overlaid with from locations I/O to I/O.

- I0.0 copy in math operation
- R0.0 overflow in math operation
- R0.2 zero in math operation
- R0.7 sign in math operation
- I0.0 first scan of program file
- R the scan time (ms)
- I0.0 year
- I0.0 month
- I0.0 day
- I0.0 hour
- I0.0 minute
- I0.0 second
- I0.0 switching output
- I0.0 fault number file number
- I0.0 I0.1 (selectable start interrupt) output
- I0.1 I0.0 file number
- I0.1 I0.1 I0.2 I0.3 I0.4 (Program and/or input interrupt) settings
- I0.1 I0.1 scan time (ms)
- I0.1 communication scan time (ms)

Figure 10.17 Inputs, Bits and Words for Micrologix and PLC-5s

The other status words allow more complex control of the PLC. The switching time allows a time delay, set in I2.28 so that if the PLC is waiting to switch the PLC will give a fault condition. This is very important for diagnostic purposes. When a fault occurs the program number in I2.29 will show. For example, if you have a 10-bit by one block, you can run a program that overruns from the end, if there is no program the PLC will fault. The locations from I2.40 to I2.47 are used for interrupts. Interrupts can be used to run programs at fixed time intervals, or when inputs change.

10.4.4 User Function Control Memory

Single holder logic functions can complete operations in a single scan of ladder logic. Other functions such as timers and counters will require multiple ladder logic scans to finish. While timers and counters have their own memory for control, a generic type of control memory is defined for other functions. This memory contains the bits and words in Figure 10.18. Any given function will only use some of the values. The meaning of specific bits and words will be described later when discussing specific functions.

- In memory locations a 'T' indicates true, 'F' indicates a word.
- Indirect addresses with subscripts memory values between [T+], [T-].
- Files are file arrays and are indicated with 'F'.
- Equations show equations to be typed in.
- Literal values for binary and hexadecimal values are followed by B and H.

146 PRACTICE PROBLEMS

1. Can PLC outputs can be set with hydraulic solenoid valves?
2. How many types of memory can a PLC have?
3. What are the default program memory locations?
4. How many types of number bases are used in PLC memory?
5. How are timer and counter memory similar?
6. What types of memory cannot be changed?
7. Develop Ladder Logic for a car door/seat belt safety system. When the car door is open, or the seatbelt is not done up, a buzzer will sound for 5 seconds if the key has been revolved. A red light will be activated on when the door is open and stay on for 10 seconds after it is closed, unless a key has started the ignition process.
8. Look at the manual for the status memory in your PLC and find the first word location.
9. Write ladder logic for the following problem description. When button A is pressed a value of 1000 will be stored in S7:1. When button B is pressed a value of 345 will be stored in S7:1, when it is not pressed the value of 99 will be stored in S7:1. When button C is pressed S7:1 will be added, and the result will be stored in S7:2.
10. Using the status memory locations, write a program that will flash a light for the first 10 seconds after it has been turned on. The light should flash once a second.
11. How many words are required for timer and counter memory?

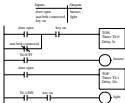
147 PRACTICE PROBLEM SOLUTIONS

1. yes, for example the output word could be addressed as a QW0.
2. There are 10 different memory types, 10 of these can be defined by the user for data files.

between 0 and 999.

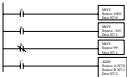
3. Program files 0 and 1 are reserved for system functions. File 2 is the default ladder logic program, and files 3 to 999 can be used for other programs.
4. Binary, word, BCD, 32-complement, signed binary, floating point, bit, hexadecimal
5. Leds are similar. The timer and counter memories hold one result for the accumulators and programs, and they use binary results the status of the functions. These bits are common but different, but parallel in function.
6. Inputs cannot be changed by the program, and some of the status bits/words cannot be changed by the user.

7.

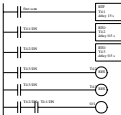


8. K2 1/14 for micrologic, K2 1/15 for PLC 3.

46.



10.



11. these memory models are used for a store or a create

11. ASSIGNMENT PROBLEMS

1. Briefly list and describe the different methods for addressing values (e.g., word, bit, block, row).
2. Could store "W" and create "C" memory types be replaced with create "W" memory types? Explain your answer.